TORQUE LIMITERS

SERIES ST | 1,000 - 160,000 Nm





THE ULTIMATE COUPLING FROM 1,000 - 160,000 Nm



SERIES ST

TORQUE LIMITERS

Areas of application for the ST

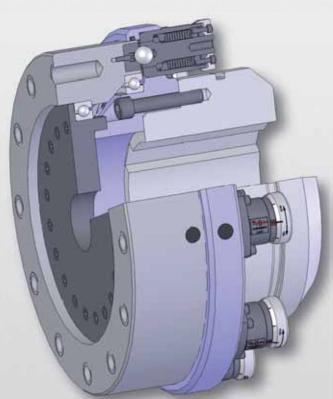
Heavy duty applications

- Rolling mills
- Dredgers
- Steel mills
- Industrial shredders
- Industrial conveyors
- Wind turbines
- Extruders
- Wastewater management
- Tunnel boring machines
- and much more

Features of the ST

- Compact, simple design
- Full disengagement
- Robust
- Precise overload protection
- Torsionally rigid
- Adjustable torque setting
- Infinite life and maintenance free

RELIABLE TORQUE OVERLOAD PROTECTION



Use of ST torque limiters will minimize machine downtime due to crashes and increase the availability and productivity of your machine.

ST torque limiters are designed for high torque applications. This is achieved through the use of individual torque modules evenly spaced around the circumference of the coupling.

The ST torque limiter is based on a spring loaded, ball-detent design.

The transmittable torque is determined by the number of torque modules and their distance from the center of the coupling.

In the event of an overload, the balls exit the detents in the axial direction, resulting in a permanent separation of the drive and driven elements.

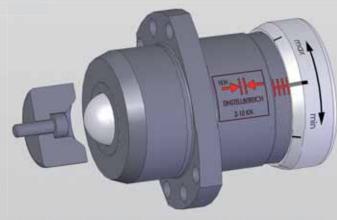
An axial force on the plunger re-engages the torque module.

The sealed torque module design prevents contamination by dirt and debris.

The torque module consists of two components.

These include the adjustable housing and plunger core.

The set torque is easily visible on a scale.



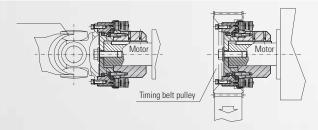


MODELS FEATURES POSSIBLE APPLICATIONS

ST 1

with keyway connection for indirect drives

- Compact, simple design
- Precise overload protection
- Torsionally rigid
- Integral bearings for timing belt pulley or sprocket



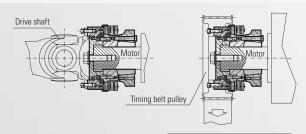
see page 4





with conical clamp connection for indirect drives

- High clamping force
- Compact, simple design
- Precise overload protection
- Torsionally rigid
- Integral bearings for timing belt pulley or sprocket



see page 5

ST₂



with keyway connection and elastomer coupling

- Vibration damping
- Compensation for misalignment
- Precise overload protection



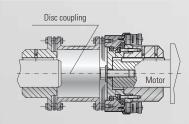
see page 8

ST3



with keyway connection and disc coupling

- Torsionally rigid
- Compensation for misalignment
- Precise overload protection



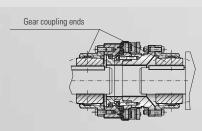
see page 7

ST 4



with keyway connection and gear coupling

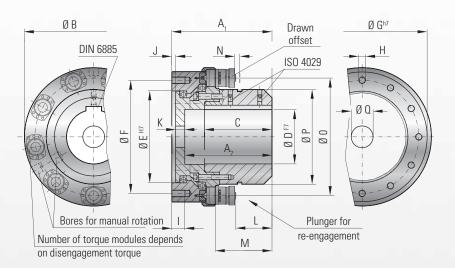
- High torque density
- Compensation for misalignment
- Precise overload protection



see page 10



TORQUE LIMITER





Material:

High-strength, nitro-carburized steel

<u>Drive side:</u> Coupling hub with keyway connection or spline profile.

Driven side: Output flange with 12x fastening threads and integral bearings.

Torque modules: Evenly spaced around the circumference. Field adjustable within the selected range.

Temperature range:

-30 to +120° C

Service life:

Infinite life and maintenance free when operated within the technical specifications.

Fit tolerance:

Tolerance between hub and shaft $0.02-0.07\ mm$

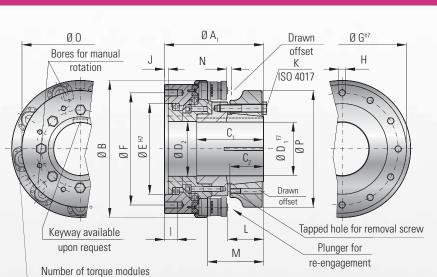
MODEL CT 4						Sei	ries							
MODEL ST 1				10			25			60			160	
Adjustment range			1-6	2-10	6-18	2-8	4-15	10-25	8-18	15-35	30-60	20-50	40-100	80-160
available from - to	(KNm)		3 x ST 15	6 x ST 15	9 x ST 15	3 x ST 15	6 x ST 15	9 x ST 15	3 x ST 30	6 x ST 30	9 x ST 30	3 x ST 70	6 x ST 70	9 x ST 70
Overall length	(mm)	A ₁		183			230		320				410	
Bore depth	(mm)	A ₂		158			200			275		360		
Flange outside diameter	(mm)	В		270			318			459		648		
Fit length	(mm)	С		120			155			220		290		
Bore diameter possible Ø to Ø F7	(mm)	D		40-110			60-140			80-200		100-290		
Flange centering diameter H7	(mm)	Е		170			210			300		450		
Bolt circle diameter ±0.3	(mm)	F		220			260			360		570		
Outside diameter h7	(mm)	G		259			298			418		618		
Fastening threads		Н		12 x M16			12 x M16			12 x M20			12 x M24	
Thread depth	(mm)			25			30			35			40	
Fit length	(mm)			6			8			8		11		
Wall thickness	(mm)	K		17		20		30			38			
Distance	(mm)	L		45			83		96			134		
Distance	(mm)	М		95			130		165				225	
Actuation path	(mm)			4			4			7,5			10	
Bolt circle diameter - modules	(mm)	0		220			270			376			532	
Hub outside diameter	(mm)			170			218			295			418	
Bore for fastening screw	(mm)	Q		max. 110		max. Ø 140			max. Ø 200			max. Ø 290		
Moment of inertia (approx.) D max.(10 ⁻³ kgm²)			370		780		4600			24600			
Speed max.	(1/min.)			4200		3800		2500			2000			
Allowable max. radial force standar	d* (KN)			40			60		100			200		
Approx. weight at D max.	(kg)			40			63			179			463	

^{*} higher radial force through additional bearing support.



depends on disengagement torque

TORQUE LIMITER





with backlash free conical clamping connection

Material:

High-strength, nitro-carburized steel

Design

<u>Drive side:</u> Coupling hub with tapered conical clamping connection

<u>Driven side:</u> Output flange with 12x fastening threads and integral bearings.

<u>Torque modules:</u> Evenly spaced around the circumference. Field adjustable within the selected range.

Temperature range:

-30 to +120° C

Service life:

Infinite life and maintenance free when operated within the technical specifications.

Fit tolerance:

Tolerance between hub and shaft $0.02-0.07\ mm$

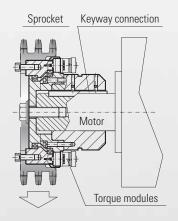
MODEL CTAL								Sei	ries					
MODEL STN				10		25				60			160	
Adjustment range available from - to	(KNm)		1-6 3 x ST 15	2-10 6 x ST 15	6-18 9 x ST 15	2-8 3 x ST 15	4-15 6 x ST 15	10-25 9 x ST 15	8-18 3 x ST 30	15-35 6 x ST 30	30-60 9 x ST 30	20-50 3 x ST 70	40-100 6 x ST 70	80-160 9 x ST 70
Overall length	(mm)	A ₁		210			227			318	ı		425	
Flange outside diameter	(mm)	В		270			318		459			648		
Fit length / keyway length	(mm)	C,		147			152			218		305		
Effective clamping length	(mm)	$C_{\scriptscriptstyle 2}$		62			67	67		93		125		
Bore diameter possible Ø to Ø F7	(mm)	D ₁		65 - 110			70 - 150	70 - 150		80 - 200		140 - 290		
Bore diameter max. Ø F7 with keyway	y (mm)	D ₁		100			140			180			270	
Inside diameter	(mm)	D ₂		110,2			140,2			200,2			290,2	
Flange centering diameter H7	(mm)	Е		170			210			300		450		
Bolt circle diameter ±0.3	(mm)			220			260			360		570		
Outside diameter h7	(mm)			259			298			418			618	
Fastening threads		Н		12 x M16			12 x M16			12 x M20			12 x M24	
Thread depth	(mm)			25			30			35		40		
Fit length	(mm)	J		6		8		8		10				
Tightening screw ISO 4017		K		8 x M16			9 x M16			8 x M20			8 x M24	
Tightening torque	(Nm)	, ,		180			180			300			710	
Distance	(mm)	L		72			80			94			151	
Distance	(mm)	М		122			127			163			240	
Actuation path	(mm)	N		4			4			7,5			10	
Bolt circle diameter - modules	(mm)	0		220			270			376			532	
Hub outside diameter	(mm)	Р		218			278			378			535	
Moment of inertia (approx.) D max.(10	D-3 kgm²)			446			789			5700			30700	
Speed max.	(1/min.)			4200			3800		2500			2000		
Allowable max. radial force standard	* (KN)			40			60		100			200		
Approx. weight at D max.	(kg)			50			65			200			550	

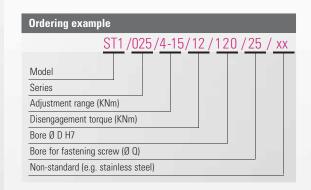
^{*} higher radial force through additional bearing support.



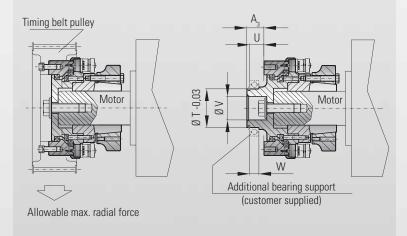
MODEL ST1/STN

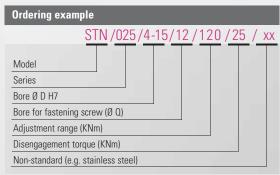
Mounting example with sprocket and keyway connection



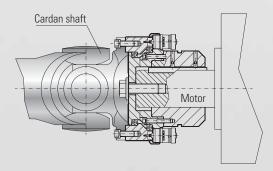


Mounting example with timing belt pulley and conical clamping hub

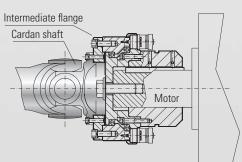




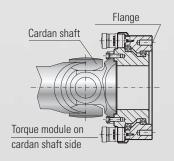
Mounting example for cardan shafts



Bolt circle and centering diameter are matched to the cardan shaft.



Mounting with intermediate flange.



Flange mounting on both sides possible.



Designs for Direct Drives

with integral elastomer jaw coupling

MODEL ST 2



Torque 1,000 - 160,000 Nm

Features

- Vibration damping
- Compensation for axial, lateral, and angular misalignment
- Robust
- Mounts axially

see pages 8/9

with integral disc pack coupling

MODEL ST3



Torque 1,000 - 160,000 Nm

Features

- Torsionally rigid for precise torque transmission
- Compensation for axial, lateral, and angular misalignment
- Low restoring forces
- Wear and maintenance free

upon request

with integral gear coupling

MODEL ST 4



Torque 1,000 - 160,000 Nm

Features

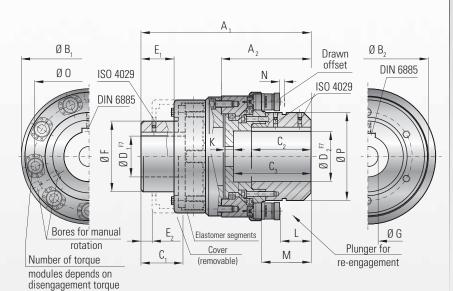
- High torque density
- Compensation for axial, lateral, and angular misalignment
- Low restoring forces
- Robust

see page 10

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TORQUE LIMITER





with integral elastomer coupling

Material:

Torque limiter: High-strength, nitro-carburized steel

Elastomer segments: precision molded, wear resistant rubber compound (75-80 Shore A) Elastomer coupling: coupling hubs made from high-strength, cast steel (coated)

Design: with keyway or spline connection. Elastomer segments for misalignment compensation. Torque modules evenly spaced around the circumference. Field adjustable within the selected range.

Temperature range: see page 9

Service life: Infinite life and maintenance free when operated within the technical specifications.

Fit tolerance:

Tolerance between hub and shaft 0.02 – 0.07 mm

Balancing: Standard balancing G16 (higher speeds upon request)

MODEL ST 2								Sei	ries					
WIODEL 31 Z			10			25			60			160		
Adjustment range			1-6	2-10	6-18	2-8	4-15	10-25	8-18	15-35	30-60	20-50	40-100	80-160
available from - to	(KNm)		3 x ST 15	6 x ST 15	9 x ST 15	3 x ST 15	6 x ST 15	9 x ST 15	3 x ST 30	6 x ST 30	9 x ST 30	3 x ST 70	6 x ST 70	9 x ST 70
Overall length ±2	(mm)	A ₁		360			437			580		730		
Length of torque limiting portion	(mm)	A ₂		183			230			320			410	
Flange OD (ST portion)	(mm)	B ₁		270			318			459			648	
Flange OD (elastomer portion)	(mm)	B ₂		290			330			432		553		
Fit length/keyway length D1	(mm)	C ₁		97			116			160			230	
Fit length/keyway length D2	(mm)	$C_{\scriptscriptstyle 2}$		120			155			220		290		
Bore depth (torque limiting portion)	(mm)	C_3		158			200			275		360		
Bore diameter (elastomer portion) Ø –	diameter (elastomer portion) Ø – Ø F7 (mm) D ₁ 40-105*			60-130*		80-		80-160*		100-200*				
Bore diameter (torque limiting portion) Ø -	– Ø F7 (mm)	$D_{_2}$	D ₂ 40-110			60-140			80-200			100-290		
Length to cover	(mm)	E,		70			87			112			152	
Length to (cover removed)	(mm)	E ₂		22			26			40			65	
Hub diameter	(mm)	F		160			200			255			300	
Bore for fastening screw	(mm)	G		max. 110		max. 140		max. 200				max. 290		
Distance	(mm)	L		45		83		96			136			
Distance	(mm)	М		95		130		165			225			
Actuation path	(mm)	N		4			4		7.5			10		
Bolt circle diameter ST	(mm)	0		220			270		376				532	
Hub outside diameter	(mm)	Р		170			218			295			418	
Moment of inertia (approx.) D max.	(10 ⁻³ kgm ²)			854			1850			8960			36858	
Speed max.	(1/min.)			2700			2300			1800			1500	
Approx. weight at D max.	(kg)			80			115		287				729	
Axial 📲 🗘	(mm)			1.5			1.5		2			2.5		
Lateral [1]	(mm)			0.4		0.5		0.6			0.7			
Angular [1]	(Degrees)			1			1		1			1		
Dynamic torsional stiffness at T_{KN} (Standard A Insert) (1	0 ³ Nm/rad)			145			230		580		1000			

^{*} larger bore diameters upon request.

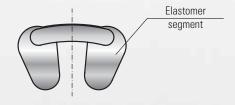


The elastomer segments

The compensating element of the ST2 torque limiters are the elastomer segments. These transmit the torque, while damping vibrations. The elastomer segments determine the properties of the entire coupling. The elastomer segments will also compensate for lateral, axial, and angular misalignment.

The standard elastomer segment is the type "A". Three different types are available.

Туре	Relative damping (ψ)	Temperatur constant	e range peak	Material	Shore hardness	Features
A (Standard)	1,0	-40°C to +80°C	+90°C	Natural and synthetic rubber	75-80 Shore A	Very high wear resistance
В	1,0	-40°C to +100°C	+120°C	Synthetic rubber	73-78 Shore A	Resistant to mineral oils and power fuel
С	1,0	-70°C to +120°C	+140°C	Silicone rubber	70-75 Shore A	High temperature range

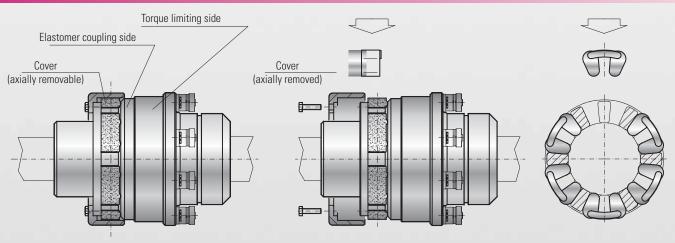


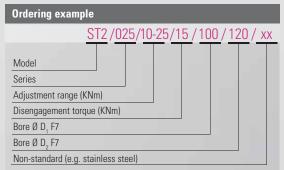
Note: Elastomer segments can easily be changed after installation.

Every coupling utilizes 6x elastomer segments.

The elastomer segments do not need to be installed prior to installation.

Changing the elastomer segments

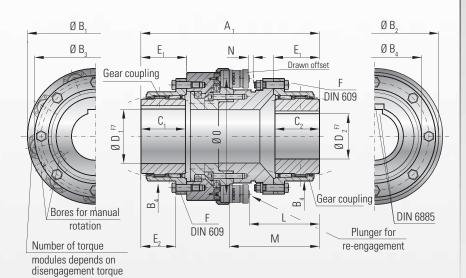




For easier handling, the coupling will be shipped unassembled.



TORQUE LIMITER





with integral gear coupling

Material:

Torque limiter: High-strength, nitro-carburized

Gear coupling ends: Extremely wear resistant tooth geometry made from high-strength alloyed steel (surface nitro-carburized)

Design: with keyway or spline connection. Gear coupling for misalignment compensation. Torque modules evenly spaced around the circumference. Field adjustable within the selected range.

Temperature range: -30 to +120° C

Service life:

Infinite life and maintenance free when operated within the technical specifications.

Fit tolerance:

Tolerance between hub and shaft 0.02 – 0.07 mm

Balancing: Standard balancing G16 (higher speeds upon request)

MODEL CT 4								Sei	ries							
MODEL ST 4				10			25			60			160			
Adjustment range			1-6	2-10	6-18	2-8	4-15	10-25	8-18	15-35	30-60	20-50	40-100	80-160		
available from - to	(KNm)		3 x ST 15	6 x ST 15	9 x ST 15	3 x ST 15	6 x ST 15	9 x ST 15	3 x ST 30	6 x ST 30	9 x ST 30	3 x ST 70	6 x ST 70	9 x ST 70		
Overall length	(mm)	A ₁		377			430			615			850			
Flange OD (ST portion)	(mm)	В,		270			318			459		648				
Mounting flange (ST portion)	(mm)	B ₂		259			298			418			618			
Flange diameter (gear coupling)	(mm)	B ₃		234			274			380		506				
Hub diameter (gear coupling)	(mm)	B ₄		181			209			307		426				
Fit length/keyway length	(mm)	C _{1/2}		90			105			150		220				
Bore diameter Ø – Ø F7	(mm)	D _{1/2}		40-112*			55-132*		90-198*		90-198*			150-27		
Length	(mm)	E,		92.5			108			154			225			
Length	(mm)	E ₂		70			79			116			196			
Screw DIN 609 12.9	(mm)	F		8 x M16			8 x M20			10 x M20			16 x M24			
Tightening torque	(Nm)	Г		280			650			650		1100				
Distance	(mm)	L		146			172			237		320				
Distance	(mm)	М		196			222			306		412				
Actuation path	(mm)	N		4			4			7.5			10			
Bolt circle diameter ST	(mm)	0		220			270			376			532			
Moment of inertia (approx.) D max.	[10 ⁻³ kgm²)			545			1298			7547			39742			
Speed max.	(1/min.)			2700			2300			1800			1500			
Approx. weight at D max.	(kg)			69			115			325			870			
Axial 🗐 🗘	(mm)			4			5		6			8				
Lateral (1)	(mm)			6			7			8		10				
	(Degrees)			1.2			1.2		1.2			1.2				

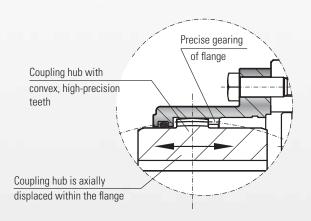
^{*} larger bore diameters upon request.



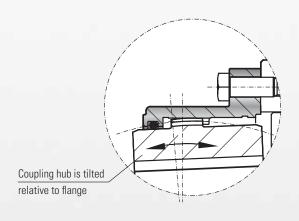
Function of the gear coupling

Shaft misalignment is compensated for through the high precision gearing of the coupling hub and flange. The gearing transmits the torque with minimal backlash and a high degree of torsional rigidity. The precise geometry of the gearing ensures the performance of the coupling.

The gearing compensates for lateral, angular, and axial misalignment.

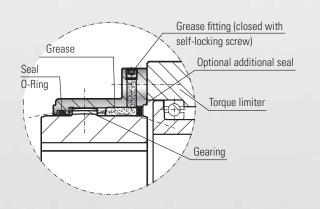


Axial misalignment



Angular and lateral misalignment

Maintenance and lubrication



Ordering example
ST4/025/10-25/15/100/120/xx
Model Series Adjustment range (KNm)
Disengagement torque (KNm)
Bore Ø D ₁ F7
Bore Ø D ₂ F7
Non-standard (e.g. stainless steel)

Recommended Iubricants

Note: The lubrication of the gearing is very important to the service life of the gear coupling.

An additional seal (optional) ensures the lubrication of the gearing over a long period of time.

Lubricant: High performance grease

Normal sp		High speed and operating load				
Castrol	Impervia MDX	Caltex	Coupling Grease			
Esso	Fibrax 370	Klüber	Klüberplex GE 11-680			
Klüber	Klüberplex GE 11-680	Mobil	Mobilgrease XTC			
Mobil	Mobilux EPO	Shell	Albida GC1			
Shell	Alvania grease EP R-O or ER 1	Texaco	Coupling Grease			
Total	Specis EPG					

For easier handling, the coupling will be shipped unassembled.

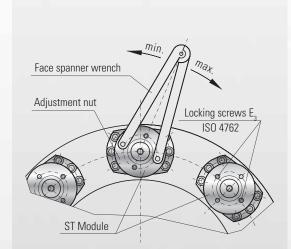


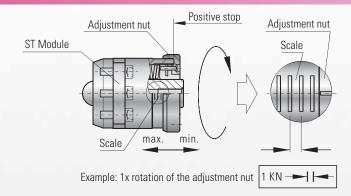
MODEL ST1/STN/ST2/ST3/ST4

TORQUE LIMITER

Mounting Instructions

Torque adjustment



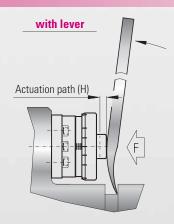


After loosening (approx. 1 rotation) the locking screws (E_3) , the adjustment nut be turned to adjust the disengagement setting. The adjustment is limited by a positive stop at the max setting. The upper value at min. is marked on the adjustment scale. After adjustment, the torque setting is secured by tightening the locking screws (E_3) .

Note: All torque modules must be set to the same value.

Re-engagement of the torque modules

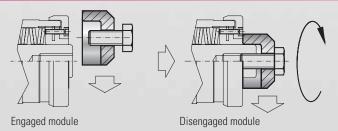
Re-engagement position markings Disengaged module Actuation path (H) Restoring force (F)



After the overload has been cleared, the drive and driven side must be rotated until the re-engagement position markings are lined up. The modules can only be re-engaged in this position.

The module is re-engaged through applying an axial force to the plunger. You will hear the module re-engage. Once this is complete, the torque limiter is ready for operation.

Manual disengagement of modules



Prior to machine start-up, the individual modules can be manually disengaged in an assembled state. A manual disengagement tool is available from R+W for this task (see page 13).

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MODEL ATEX

FOR USE IN EXPLOSIVE ATMOSPHERES

Regulated under the new European directive, ATEX 95a. Explosive atmospheres are classified into 3 different zones.

Zone 0: An explosive atmosphere consisting of a mixture of air and flammable substances, in the form of a gas, vapor, or mist, that is present frequently, continuously, or for extended periods of time.

Zone 20: An explosive atmosphere consisting of clouds of combustible dust in the air under the same conditions above.

Zone 1: An explosive atmosphere consisting of a mixture air and flammable substances, in the form of gas, vapor, or mist, that is likely to occur in normal operation occasionally.

Zone 21: An explosive atmosphere consisting of clouds of combustible dust in the air under the same conditions above.

Zone 2: An explosive atmosphere consisting of a mixture air and flammable substances, in the form of gas, vapor, or mist, that is unlikely to occur in normal operation, but would only persist for a short period of time if it were to occur.

Zone 22: An explosive atmosphere consisting of clouds of combustible dust in the air under the same conditions above.

For zones 1/21 and 2/22, ST-EEx torque limiters can be supplied with ATEX 95a accreditation.

Mounting and operating instructions:

Detailed mounting and instruction manuals are supplied with the ST-EEx torque limiters.

The following information is included:

- Assembly of the ST-EEx torque limiter
- Precise tightening torques and misalignment ratings
- Details covering proper implementation
- Maintenance
- Inspection intervals
- Troubleshooting
- Coupling identification markings
- Certificate of conformance

Identification:

All ST-EEx torque limiters are inscribed with manufacturer and accreditation information.

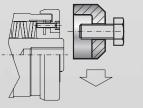
Accreditation information example:



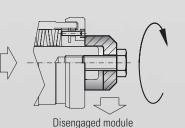
Typ: ST4 25 EEx-2009 II 2 G D EEx fr c T3 / 135°C Ser.No.: A 200101.1 Tech.Ref.No.:2009/008RW

ACCESSORIES

Engagement / disengagement tool



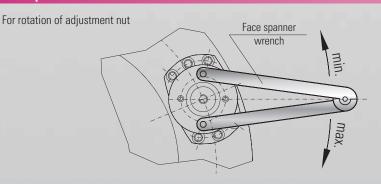
Engaged module



Order-No.: see table

Series	Engagement / disengagement tool
15	Order-No. AV/0015
30	Order-No. AV/0030
70	Order-No. AV/0070
	Order-No. AV/0015 Order-No. AV/0030

Face spanner wrench



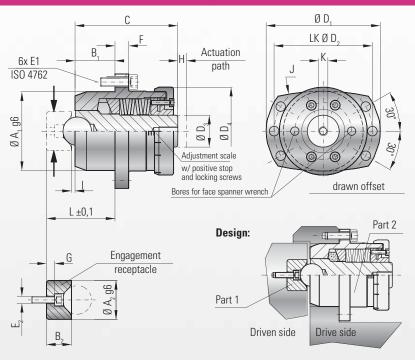
Order-No.: see table

Series	Face spanner wrench
15	Order-No. SLS/0015
30	Order-No. SLS/0030
70	Order-No. SLS/0070





TORQUE MODULE



Material: High-strength, nitro-carburized steel **Design:** Two part assembly for installation into prefabricated coupling components.

Part 1: Engagement receptacle

Part 2: Module with self-contained, spring loaded

The spring tension is adjustable in the field. The set force is visible on the adjustment scale.

Temperature range: -30 to +120° C

Service life: Infinite life and maintenance free when operated within the technical specifications.

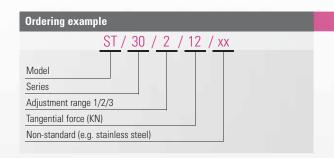
Fit tolerance: For mounting of the ST torque modules, an H7 bore tolerance is required.

Re-engagement: The modules are re-engaged by applying an axial force to the plunger when a synchronized angularity of the drive and driven side is present.

MODEL CT				Series	
MODEL ST			15	30	70
T			1-4	5-10	8-20
Tangential force (KN) Adjustment range available from - to	(ranges)	2	2-8	10-20	15-40
,	(9)	3	6-20	20-35	30-70
Centering diameter torque module g6	(mm)	A ₁	40	70	90
Centering diameter engagement receptacle g6	(mm)	A ₂	24	34	44
Centering length torque module	(mm)	B ₁	20	35	45
Centering length engagement receptacle	(mm)		14	22	30
Overall length	(mm)		70	103	135
Outside diameter	(mm)	D,	59	100	129
Bolt circle diameter	(mm)		50	86	110
Diameter plunger	(mm)		16	28	35
Diameter adjustment nut	(mm)		44	75	92
Screw / tightening torque ISO 4762	(mm)		6 x M5 x 16 / 10 Nm	6 x M8 x 25 / 40 Nm	6 x M12 x 35 / 120 Nm
Screw / tightening torque ISO 4762	(mm)		M4 x 14 4.5 Nm	M6 x 20 15.5 Nm	M8 x 25 38 Nm
Flange thickness	(mm)		7	12	16
Distance	(mm)		5	8	10
Actuation path	(mm)		4	7.5	10
Distance	(mm)		2	3	4
Radius	(mm)		110	200	250
Inner thread	(mm)		M8 x 15	M10 x 25	M16 x 30
Distance ± 0,1	(mm)		36	60	79
Weight	(kg)		0.65	2.7	6

axial spring force ≈ tangential force/1.4





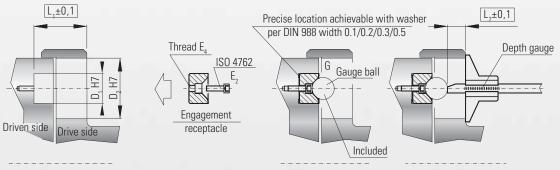
Maintenance

The ST modules are lubricated and sealed for life. Routine maintenance is not required. The modules have an extreme service life, however, after several disengagements, the function of the modules should be checked.

Mounting instructions ST

Mounting engagement receptacle

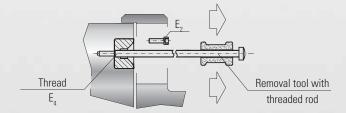
Note: Measurements L1 and L2 must be checked prior to installing the torque modules.



Dismounting of engagement receptacle

Mounting of torque module

After loosening the mounting screw E2, the engagement receptacle can re dismounted with a removal tool.



Note: Prior to mounting the torque module, the ball seat must be lubricated (e.g. Klüber Isoflex Topas NB 52).

MODEL CT			Series	
MODEL ST		15	30	70
Screws	E,	6 x M5 x 16 (12.9)	6 x M8 x 25 (12.9)	6 x M12 x 35 (12.9)
Tightening torque	'	10 Nm	40 Nm	120 Nm
Screws	Ε,	1 x M4 x 12	1 x M6 x 20	1 x M8 x 25
Tightening torque	2	4,5 Nm	15,5 Nm	38 Nm
Screws	E,	4 x M4 x 14	4 x M4 x 16	4 x M5 x 20
Tightening torque	3	4,5 Nm	4,5 Nm	10 Nm
Thread	$E_{_{\!4}}$	M5	M8	M10
Actuation path	Н	4 mm	7,5 mm	10 mm
Restoring force	F	max. 2 KN	max. 4 KN	max. 6 KN
Fit length	L ₁ ±0,1	36	60	79
Depth measurement	L ₂ ±0,1	10	20,5	29
Gauge ball	ØG	16	25	30



According to disengagement torque

As a rule, torque limiters are rated according to the required disengagement torque, which must be greater than the necessary operating torque.

The disengagement torque is determined according to the drive specifications.

The following formula provides a basis for calculation:

$T_{AR} \ge K \cdot T_{max} (Nm)$	$T_{\Delta R}$	≥K		T_{max}	(Nm)
-----------------------------------	----------------	----	--	-----------	------

K = 1.3 uniform load

K = 1.5 light, non-uniform load

K = 1.8 heavy, non-uniform load

$$T_{Drive} \ge 9550 \cdot \frac{P_{Drive}}{N}$$
 (Nm)

= Disengagement torque of coupling (Nm)

 $\begin{matrix} T_{_{AR}} \\ K \end{matrix}$ = service factor

(Nm) = peak operating torque

= Nominal torque of drive (Nm) = Drive power (kW) = Drive speed (min -1)

According to acceleration torque (start-up at no load)

Shock or load factor

 $S_A = 1$ (uniform load)

 $S_A = 2$ (non-uniform load)

 $S_{\Delta} = 3$ (highly dynamic load)

$$T_{AR} \ge \alpha \cdot J_L \ge \frac{J_L}{J_A + J_I} \cdot T_{AS} \cdot S_A$$
 (Nm)

= Disengagement torque of coupling (Nm) T_{AR}

= Angular acceleration

α

 $\alpha = \frac{\omega}{t} = \frac{\pi \cdot n}{t \cdot 30}$

(sec.)

= Acceleration time t

= Angular velocity (1/s)ω

n = Drive speed (min-1)

= Moment of inertia on load side (kgm²)

= Moment of inertia on drive side (kgm²)

= Peak torque of motor (Nm)

According to acceleration and load torque (start-up with load)

$$T_{AR} \geqq \alpha \cdot J_L + T_{AN} \geqq \left\lceil \frac{J_L}{J_A + J_L} \cdot (T_{AS} - T_{AN}) + T_{AN} \right\rceil \cdot S_A \ \ (Nm)$$

= Disengagement torque of coupling (Nm) T_{AR} = Angular acceleration α

 $\alpha = \frac{\omega}{t} = \frac{\pi \cdot n}{t \cdot 30}$

= Acceleration time (s)

 Angular velocity (1/s)

= Drive speed (min -1)

= Moment of inertia on load side (kgm²)

= Load torque (Nm) = Moment of inertia on drive side

(kgm²)

= Peak torque of motor (Nm)

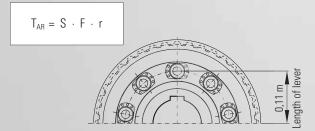
According to number of torque modules

Shock or load factor

 $S_{\Delta} = 1$ (uniform load)

 $S_A = 2$ (non-uniform load)

 $S_A = 3$ (highly dynamic load)



= Disengagement torque of coupling (Nm) S = Number of torque modules

= Tangential force

(m)

= Length of lever

(KN)



According to linear feed force

Spindle drive

$$T_{\text{AN}} = \frac{s \cdot F_{\text{V}}}{2000 \cdot \pi \cdot \eta} \quad \text{(Nm)}$$

Timing belt drive

$$T_{AN} = \frac{d_0 \cdot F_V}{2000} \quad (Nm)$$

 T_{AN} = Load torque (Nm)

= Pitch (mm)

 $v_{\rm v}$ = Linear feed force (N)

η = Efficiency factor

 T_{AN} = Load torque (Nm)

 $d_0 = Gear diameter (timing belt pulley)$ (mm)

= Linear feed force (N)

According to resonant frequency

The resonant frequency of the coupling must be higher or lower than the frequency of the machine.

The following calculation is used for a 2 mass system:

$$f_e = \ \frac{1}{2 \cdot \pi} - \sqrt{C_T \ x \ \frac{J_{Machine} + J_{Mot}}{J_{Machine} \cdot \ J_{Mot}} \ (Hz)}$$

 C_{τ} = Torsional stiffness of coupling (Nm/rad)

J_{Masch.} = Moment of inertia total machine (kgm²) (Spindle + carriage + components + coupling half)

 J_{Mot} = Moment of inertia motor (kgm²) (Rotor + coupling half)

f_o = Resonant frequency of 2 mass system (Hz)

Specifications of elastomer jaw coupling ST2

Series		ST2 / 10	ST2 / 25	ST2 / 60	ST2 / 160
T _{KN} Rated torque (I	Vm)	10,000	15,000	40,000	80,000
T _{Kmax} Peak torque (I	Nm)	22,000	33,000	88,000	176,000
Dynamic torsional stiffness (10 ³ Nm/	rad)	145	230	580	1000
Relative damping		1	1	1	1

Rating factors

Shock or load factor S

A	Load variables of machine				
Drive	G	M	S		
Electric motors, turbines, hydraulic motors	1.25	1.6	2.0		
Internal combustion engines ≥ 4 cylinders Degree of uniformity ≥ 1:100	1.5	2.2	2.5		

G = Uniform load, M = Average load, S = Heavy load

Temperature factor S

Ambient temperature	-40 C° +30 C°	+40 C°	+60 C°	+80 C°	>+80 C°
S _t	1.0	1.1	1.4	1.8	upon request

Start factor S

otart rabtor o _z					
Start frequency per hour	30	60	120	240	>240
S_7	1.0	1.1	1.2	1.3	upon request

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According to torque

1. Calculation of drive torque T_{DR} .

$$T_{DR}[Nm] = 9550 \frac{P[kW]}{n[rpm]}$$

2. Calculation of the rated torque of the coupling based on drive torque T_{DR} considering all rating factors.

$$T_{KN} \ge T_{DR} \times S_A \times S \times S_7$$

Selection example:

Calculation of coupling for use between an electric motor (P= 450 kW at 980 rpm) and belt conveyor.

Uniform load present 40°C : S = 1.1 Ambient temperature 30/h : $S_{x} = 1.0$ Start frequency

$$T_{DR} = 9550 - \frac{450 \text{ kW}}{980 \text{ rpm}} = 4385.2 \text{ Nm}$$

$$\begin{array}{l} T_{_{KN}} \geq T_{_{DR}} & x \quad S_{_{A}} & x \quad S \quad x \quad S_{_{z}} \\ T_{_{KN}} \geq 4385.2 \; Nm \quad x \quad 1.25 \quad x \quad 1.1 \quad x \quad 1.0 \; = \; 6029.7 \; Nm \end{array}$$

Selected coupling: ST2/10 with $T_{KN} = 6030 \text{ Nm}$

Classification of load by type of machine

Excavators

- S bucket-chain excavators
- S traveling gear (caterpillar)
- M traveling gear (rails)
- M suction pumps
- S bucket wheels
- M slewing mechanisms

Construction machines

- M concrete mixers
- M road construction machines

Chemical industry

- M mixers
- G agitators (light fluids)
- M dryer drums
- G centrifuges

Conveyor systems

- S conveyor machines
- G belt conveyors (bulk materials)
- M band pocket conveyors
- M chain conveyors
- M circular conveyors
- M hoists
- G flour bucket conveyors
- M screw conveyors
- M gravel bucket conveyors
- M steel belt conveyors
- 1) P = Power of drive in kW n = speed in rpm

Blowers, ventilators1

- G blowers (axial/radial) P:n ≤ 0.007
- M blowers (axial/radial) P:n ≤ 0.007
- S blowers (axial/radial) P:n ≤ 0.007
- G cooling tower fans $P:n \le 0.007$
- M cooling tower fans $P:n \le 0.007$
- S cooling tower fans $P:n \le 0.007$

Generators, converters

S generators

Rubber machinery

- S extruders
- S kneading mills
- M mixers
- S rolling mills

Woodworking machines

G woodworking machines

Cranes

- S traveling gear
- S lifting gear
- M slewing mechanisms

Plastics machines

- M mixers
- M shredders

Metalworking machines

- M sheet metal bending machines
- S plate straightening machines

- S presses
- M shears
- S stamp punches
- M machine tools, main drives

Food processing machines

- G filling machines
- M kneading machines
- M sugarcane crushers
- M sugarcane cutters
- S sugarcane mills
- M sugar beet cutters
- M sugar beet washers

Paper machines

- S wood cutters
- S calenders
- S wet presses
- S
- suction presses
- suction rollers
- S drying cylinders

Pumps

- S piston pumps
- G rotary pumps
- S plunger pumps

Stone, clay

- S crushers
- S rotary kilns

- S hammer mills
- S brick presses

Textile machines

- M tanning vats
- M willows
- M looms

Compressors

- S piston compressors
- M turbo-compressors

Rolling mills

- M plate turner
- M wire drawing mills
- S descaling breakers
- S cold-roll mills
- M chain drags
- M traverse drags
- M roller tables
- pipe welding machines
- S continuous casting machines
- M roller adjust mechanisms

Laundry machines

- M drum dryers
- M washing machines

Water treatment

- M aerators
- G water screw conveyors



Specifications of gear coupling ST4

Series		ST4 / 10	ST4 / 25	ST4 / 60	ST4 / 160
T _{KN} Rated torque	(Nm)	16,000	22,000	62,000	174,000
T _{Kmax} Peak torque	(Nm)	32,000	44,000	124,000	348,000
Grease	(dm³)	0.5	0.8	1.5	3.3
n Ref (Speed max.)	(1/min.)	6,050	5,150	3,600	3,050

^{*} only allowable at reduced torque and misalignment

Selection based on torque

1. Calculation of drive torque T_{DR}.

$$T_{AN} [Nm] = 9550 \frac{P [kW]}{n [rpm]}$$

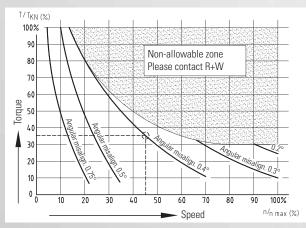
2. Calculation of the rated torque of the coupling based on drive torque $T_{\rm DR}$ considering all rating factors (Shock or load factor $S_{\rm A}$, see page 17)

$$T_{KN} \ge T_{DR} \times S_A$$

Application graph

Max torque, max speed, and max misalignment should never occur at the same time.

Calculation of T / T_{KN} and n / n_{max} Calculate values and enter and check in the diagram below.



Example: Coupling ST4/10 $T = 5600 \text{ Nm T/}_{TKN} = ---- \cdot 100 = 35\% \\ 16000 \\ n = 2700 \text{ rpmn/}_{n \text{ max}} = ---- \cdot 100 = 45\% \\ \text{Angular misalignment: 0.4} \cdot 100 = 45\% \\ \text{Model of the state of$

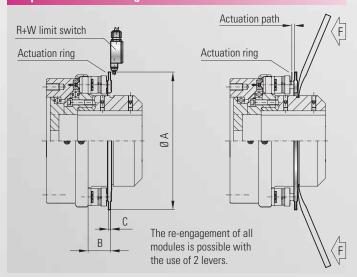
Selection example:

Calculation of a coupling for use between an electric motor (P= 1000 kW at 980 rpm) and screw conveyor (S_a = 1.6).

$$T_{DR} = 9550 - \frac{1000 \text{ kW}}{980 \text{ rpm}} = 9744 \text{ Nm}$$

Selected coupling: ST4/10 with $T_{KN} = 16,000 \text{ Nm}$

Optional actuation ring



MODEL ST 1	Series				
MIODEL 21 I	10	25	60	160	
Outside diameter	Α	278	328	upon request	upon request
Distance	В	57	57	upon request	upon request
Actuation ring thickness	С	4.5	4.5	upon request	upon request

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TORQUE LIMITERS Series SK + ST

From 0.1 – 160,000 Nm, Bore diameters 3 – 290 mm Available as a single position, multi-position, load holding, or full disengagement version Single piece or press-fit design



BELLOWS COUPLINGS Series BK

From 2 - 10,000 Nm Bore diameters 10 - 180 mm Single piece or press-fit design



LINE SHAFTS Series ZA/ZAE

From 10-4,000~NmBore diameters 10-100~mmAvailable up to 6~m length



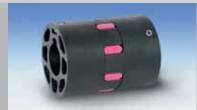
MINIATURE BELLOWS COUPLINGS Series MK

From 0.05 - 10 NmBore diameters 1 - 28 mmSingle piece or press-fit design



SERVOMAX® ELASTOMER COUPLINGS Series EK

From $2-2,000\,\mathrm{Nm}$, Shaft diameters $3-80\,\mathrm{mm}$ backlash-free, press-fit design



ECOLIGHT® ELASTOMER COUPLINGS Series TX 1

From $2-810\ Nm$ Shaft diameters $3-45\ mm$



LINEAR COUPLINGS Series LK

From 70 - 2,000 NThread M5 - M16



POLYAMIDE COUPLINGS MICROFLEX Series FK 1

Rated torque 1 Ncm Bore diameters 1 - 1.5 mm